

# Decision Procedures for Flat Array Properties

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20th International Conference on Tools and Algorithms for the  
Construction and Analysis of Systems

April 7, 2014

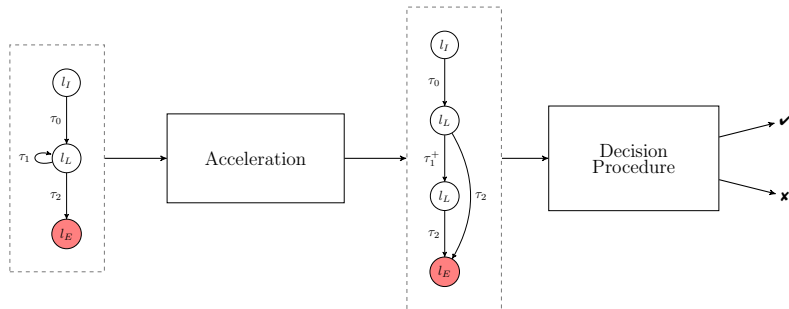
Many applications:

- Properties of the heap
- Frame axioms
- Checking user provided assertions
- Parameterized systems

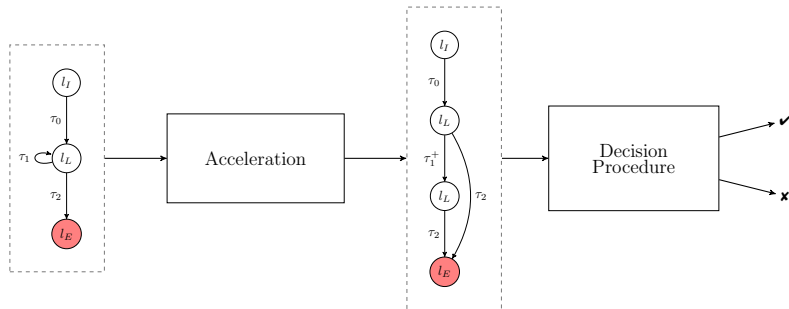
⇒ Verifying array programs:

- CEGAR-based approaches for array programs [AlbertiBG<sup>+</sup>12]
- **Accelerations of relations over arrays** [AlbertiGS13]

# Accelerations of relations over arrays



# Accelerations of relations over arrays



✓ Accelerations of a class of relation over arrays is definable via  $\exists^*\forall^*$ -formulae [AlbertiGS13]



Accelerations might be outside known decidable fragments [BradleyMS06, HabermehlIV08, GeM09].

# Accelerations of relations over arrays

$$\tau := G(i, \mathbf{a}[i]) \quad \wedge \quad i' = i + \bar{k} \quad \wedge \quad \mathbf{a}' = \text{store}(\mathbf{a}, i, \mathbf{t}(\mathbf{a}[i]))$$

⇓

$$\tau^+ := \exists y > 0. \left( \begin{array}{l} \forall j. [ i \leq j < i + \bar{k} \cdot y \wedge D_{\bar{k}}(j - i) \rightarrow G(j, \mathbf{a}(j)) ] \wedge \\ i' = i + \bar{k} \cdot y \wedge \\ \forall j. [ \mathbf{a}'(j) = \mathbf{U}(i, j, y, \mathbf{a}(j)) ] \end{array} \right)$$

# Quantified fragments of array theories

Related work

Theory of arrays: “base” theory  $T$  + free functions  $\mathbf{a}$

Fragment of interest:  $\varphi := \exists \mathbf{c} \forall \mathbf{i} \psi( \mathbf{c} , \mathbf{i} , \mathbf{a}(t) )$

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- In general, undecidable
  
- If constrained, two main strategies to show decidability:
  - 1 Instantiation-based
  
  - 2 Automata-based

Bradley et al. “What’s decidable about arrays?”, VMCAI 2006.

- Array property:  $\varphi := \forall \mathbf{i}. F(\mathbf{i}) \rightarrow G(\mathbf{a}(\mathbf{i}))$ 
  - $F(\mathbf{i})$  is a conjunction of atoms of the kind  $i \leq j, i \leq t, t \leq i$

I. Identify an *index set*  $\mathcal{I}$

II. Instantiate  $\mathbf{i}$  over  $\mathcal{I}$  to obtain a quantifier-free  $\psi_1 \wedge \dots \wedge \psi_n$

III. Standard theory-combination approaches on  $\psi_1 \wedge \dots \wedge \psi_n$

- Complexity: NEXPTIME (NP if we fix the number of index variables)



# Quantified fragments of array theories

## Related work

Habermehl et al. “A Logic of Singly Indexed Arrays”, LPAR 2008.

- $\varphi := \forall \mathbf{i}. F(\mathbf{i}) \rightarrow G(\mathbf{i}, \mathbf{a}(\mathbf{i} + \bar{\mathbf{k}}))$ 
  - No disjunctions in  $G$
  - Atoms are difference logic constraints (with equations modulo  $\bar{\mathbf{k}}$ )

- I. Translate  $\varphi$  into a FCADB<sup>1</sup>  $\mathcal{A}_\varphi$
- II. Check the emptiness of  $\mathcal{L}(\mathcal{A}_\varphi)$

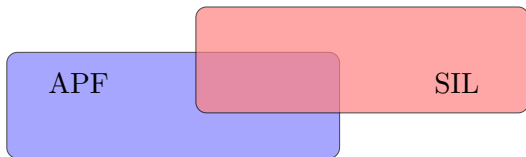
- Complexity: unknown

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<sup>1</sup>Deterministic flat counter automata with difference bound transition rules

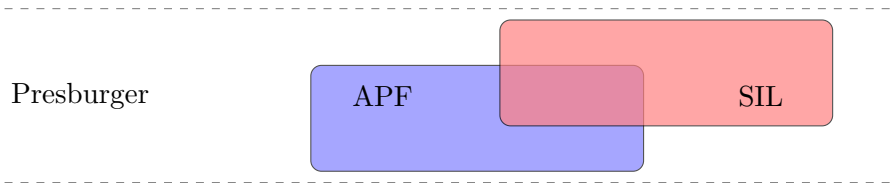
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Our contribution wrt related work



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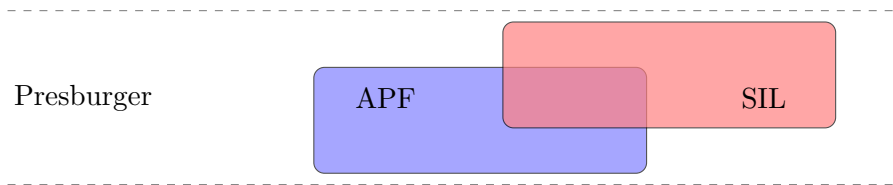
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# Quantified fragments of array theories

Our contribution wrt related work

Presburger + exp



Real Arithmetic

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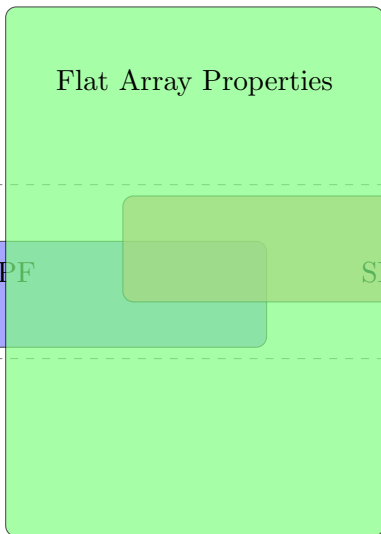
Flat Array Properties

Presburger

APF

SIL

Real Arithmetic



# Our contribution

## Flat Array Properties

- $\varphi := \exists \mathbf{c} \forall \mathbf{i}. \psi( \mathbf{i}, \mathbf{a}(\mathbf{i}), \mathbf{c}, \mathbf{a}(\mathbf{c}) )$ 
  - $a(t)$  allowed only if  $t$  is a variable

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- Mono-sorted theory:  $T \cup \{a_1, \dots, a_n\}$ 
  - $|\mathbf{i}| = 1$
  - Requirement:  $T$ -decidability of  $\exists^* \forall \exists^*$ -formulae
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- Multi-sorted theory:  $T_I \cup T_E \cup \{a_1, \dots, a_n\}$ 
  - INDEX atoms with at most one universally quantified variable
  - Requirement:  $T_I$ -decidability of  $\exists^* \forall$ -formulae
  - Requirement:  $T_E$ -decidability of quantifier-free formulae
  - Complexity if  $T_I, T_E$  are  $\mathbb{P}^+$ : NEXPTIME-complete



# Decision Procedure for the multi-sorted case

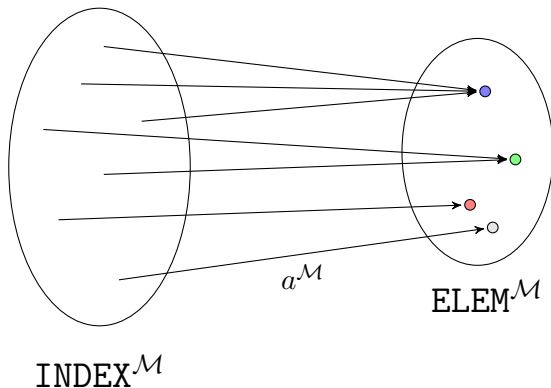
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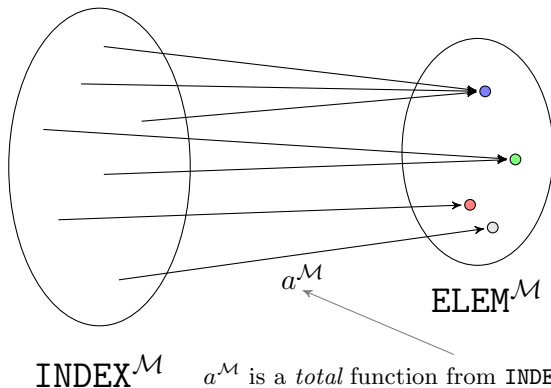
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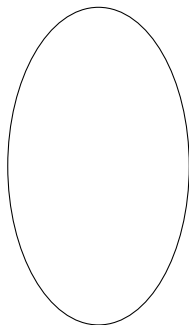
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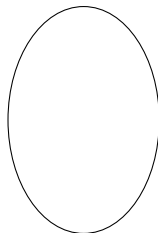
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STEP I. Guess the set of INDEX *types*



INDEX<sup>M</sup>

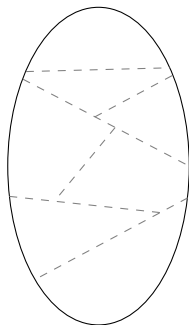


ELEM<sup>M</sup>

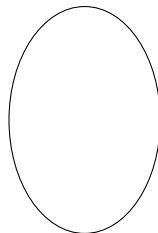
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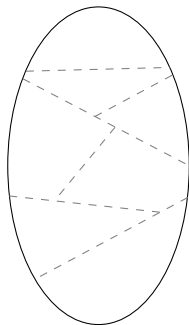
- Consider the set  $K$  of all INDEX *atoms* in  $F$  (plus equalities with the  $\mathbf{c}$  constants)
- Let  $\{M_1, \dots, M_q\}$  be the the set of *maximal* and *consistent* sets of literals built out of  $K$ 
  - Each  $L(x, \mathbf{c})$  in every  $M_h$  is an atom of  $K$  or its negation
  - All the  $M_h$ 's are mutually exclusive
- Every element of  $\text{INDEX}^{\mathcal{M}}$  has to realize a type  $M_h$ :

$$\mathcal{M}_I \models \forall x. \left( \bigvee_{j=1}^q \bigwedge_{L \in M_j} L(x, \mathbf{c}) \right)$$

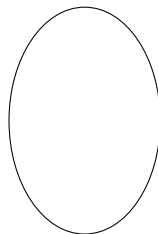
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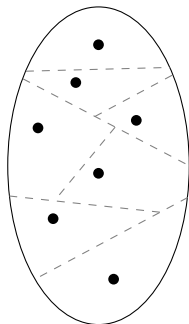


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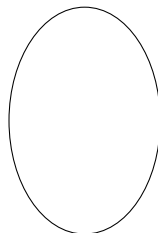
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1. Each  $b_h$  realizes the corresponding type

$$\mathcal{M}_I \models \bigwedge_{j=1}^q \bigwedge_{L \in M_j} L(b_j, \mathbf{c})$$

2. The instantiation

$$\bigwedge_{\sigma: \mathbf{i} \rightarrow \mathbf{b}} \psi( \mathbf{i}\sigma, a(\mathbf{i}\sigma), \mathbf{c}, a(\mathbf{c}) )$$

is consistent

# Decision Procedure for $\text{ARR}^2(T_I, T_E)$

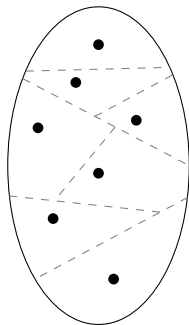
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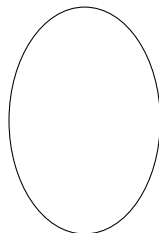
$$F_1 := \exists \mathbf{b} \exists \mathbf{c} \left[ \begin{array}{l} \forall x. \left( \bigvee_{j=1}^q \bigwedge_{L \in M_j} L(x, \mathbf{c}) \right) \wedge \\ \bigwedge_{j=1}^q \bigwedge_{L \in M_j} L(b_j, \mathbf{c}) \wedge \\ \bigwedge_{\sigma: \mathbf{i} \rightarrow \mathbf{b}} \psi(\mathbf{i}\sigma, a(\mathbf{i}\sigma), \mathbf{c}, a(\mathbf{c})) \end{array} \right]$$

# Decision Procedure for the multi-sorted case

STEP III. Substitute the tuple  $a(\mathbf{b}) * a(\mathbf{c})$  with a tuple  $\mathbf{e}$  of ELEM constants



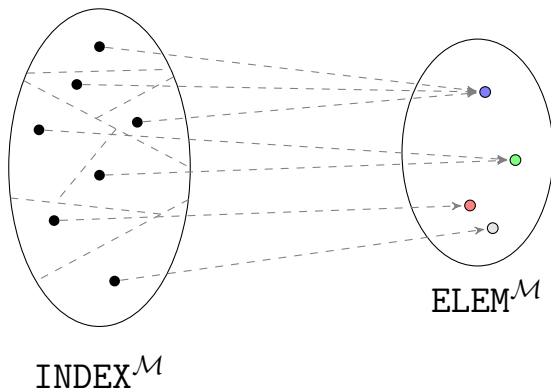
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$$a(\mathbf{b}) * a(\mathbf{c}) \rightsquigarrow \mathbf{e}$$

$$F_2 := \exists \mathbf{b} \exists \mathbf{c} \left[ \dots \wedge \bar{\psi}(\mathbf{b}, \mathbf{c}, \mathbf{e}) \wedge \bigwedge_{d_m, d_n \in \mathbf{b} * \mathbf{c}} \bigwedge_{l=1}^s (d_m = d_n \rightarrow e_{l,m} = e_{l,n}) \right]$$

functional  
consistency

# Decision Procedure for the multi-sorted case

STEP IV. “Split” the formula  $F_2$  in INDEX and ELEM parts

$$F_2 := \exists \mathbf{b} \exists \mathbf{c} \left[ \begin{array}{l} \forall x. \left( \bigvee_{j=1}^q \bigwedge_{L \in M_j} L(x, \mathbf{c}) \right) \wedge \\ \bigwedge_{j=1}^q \bigwedge_{L \in M_j} L(b_j, \mathbf{c}) \wedge \\ \bar{\psi}(\mathbf{b}, \mathbf{c}, \mathbf{e}) \wedge \bigwedge_{d_m, d_n \in \mathbf{b} * \mathbf{c}} \bigwedge_{l=1}^s (d_m = d_n \rightarrow e_{l,m} = e_{l,n}) \end{array} \right]$$

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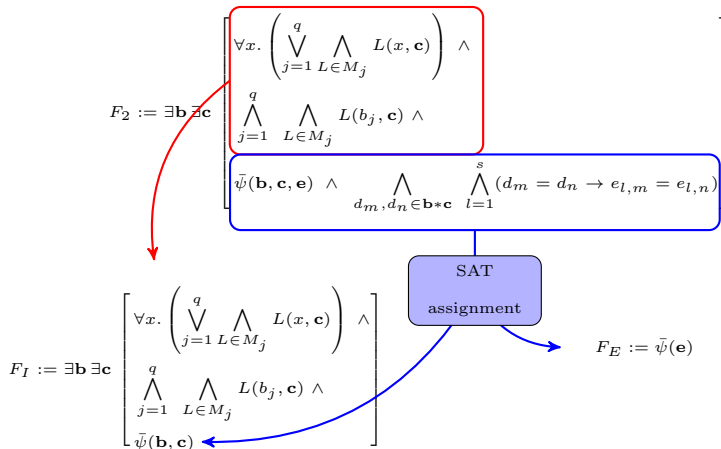
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STEP V. Check if  $F_I$  is  $T_I$ -sat and if  $F_E$  is  $T_E$ -sat

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<sup>1\*</sup> With divisibility predicates  $\{D_k\}_{k \geq 2}$ .

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$\Rightarrow$  Quantifier-free fragment

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$\Rightarrow \exists^* \forall$ -fragment

- ✓ Difference Logic\*
- ✓ Presburger\*
- ✓ Presburger\* + exp [Semënov84]
- ✓ Real Arithmetic

$\Rightarrow$  Quantifier-free fragment

...

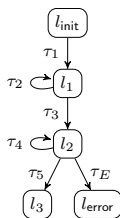
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Application: deciding the safety of  $\text{simple}_{\mathcal{A}}^0$ -*programs*

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- Flat control-flow structure
- Every loop  $\tau$  has a Flat Array Property as acceleration

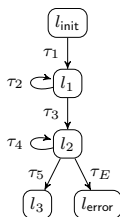




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## Theorem

*The unbounded reachability problem for  $\text{simple}_{\mathcal{A}}^0$ -programs is decidable.*

- $\text{simple}_{\mathcal{A}}^0$ -*programs*:
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  - testing
  - swapping
  - etc.

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- The SMT-Solvers Z3 and CVC4 fail on (some) proof obligations
  - especially the satisfiable ones (derived by unsafe programs)

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**Thank you! Questions?**



Francesco Alberti, Roberto Bruttomesso, Silvio Ghilardi, Silvio Ranise, and Natasha Sharygina.

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Francesco Alberti, Silvio Ghilardi, and Natasha Sharygina.

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In *FroCos*, pages 23–39, 2013.



Aaron R. Bradley, Zohar Manna, and Henny B. Sipma.

What's decidable about arrays?

In E. Allen Emerson and Kedar S. Namjoshi, editors, *VMCAI*, volume 3855 of *Lecture Notes in Computer Science*, pages 427–442. Springer, 2006.



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